Contents

List of Contributors xvii

1 Overview of Networked Control Systems
Rachana A. Gupta and Mo-Yuen Chow 1
1.1 Introduction 1
1.1.1 Advantages and Applications of Control over Network 2
1.1.2 Brief History of Research Field of NCS 4
1.2 NCS Categories and NCS Components 5
1.2.1 NCS Components 8
1.2.2 Information Acquisition in a Network 8
1.2.3 Control of Actuators over a Network 9
1.2.4 Communication 9
1.3 NCS Challenges and Solutions 10
1.3.1 Integration of Components and Distribution of Intelligence . 13
1.4 A Case Study for NCS–iSpace 14
1.5 Conclusions 20
References 21

2 Overview of Agent-based Control and Management for NCS
Fei-Yue Wang 25
2.1 Introduction 25
2.2 From Electricity to Connectivity: Why Agent-based Control and Management for Networked Systems 26
2.3 Hosting Mechanism and System Architecture for ABC 28
2.4 Design Principle for Networked Control Systems: Local Simple, Remote Complex (LSRC) 33
2.5 Modular Construction and Learning Algorithms of Neuro-fuzzy Networks for LSRC Implementation 35
2.6 Issues in Software, Middleware, and Hardware Platforms 46
2.7 Real-world Applications 50

2.8 Concluding Remarks and Future Work 51
References 53

3 Networked Control Systems: Emulation-based Design
Mohammad Tabbara, Dragan Nešić, Andrew R. Teel 57
3.1 Introduction 57
3.2 Overview of Emulation-based NCS Design 60
3.2.1 Principles of Emulation-based NCS Design 60
3.2.2 Results in Perspective 61
3.3 Modeling Networked Control Systems and Scheduling Protocols . . . 65
3.3.1 Scheduling and a Hybrid System Model for NCS 68
3.3.2 NCS Scheduling Protocol Properties 70
3.3.3 Lyapunov UGES and a.s. UGES Scheduling Protocols 71
3.3.4 PE_T Scheduling Protocols 73
3.3.5 a.s. Covering Protocols 76
3.3.6 Slotted p-Persistent CSMA 79
3.3.7 CSMA with Random Waits 80
3.4 NCS Stability 81
3.4.1 L_p Stability of NCS with Lyapunov UGES Protocols 82
3.4.2 L_p Stability of NCS with PE_T Protocols 83
3.4.3 L_p Stability of NCS with Random Protocols 84
3.4.4 L_p Stability of NCS with a.s. Lyapunov Protocols 85
3.5 Case Studies and Comparisons 86
3.5.1 Comparison of Analytical Inter-transmission Bounds 87
3.5.2 Comparison of Numerical Inter-transmission Bounds ($p_0 = 0$) 89
3.5.3 Comparison of Numerical Inter-transmission Bounds ($p_0 > 0$) 91
3.6 Conclusions 93
References 94

4 Analysis and Design of Networked Predictive Control Systems
Guo-Ping Liu 95
4.1 Introduction 95
4.2 Networked Predictive Control 97
4.2.1 Design of the Control Prediction Generator 97
4.2.2 Design of the Network Delay Compensator 101
4.2.3 Algorithm of Networked Predictive Control 102
4.3 Stability of Networked Predictive Control Systems 102
4.3.1 Fixed Network Transmission Delay 102
4.3.2 Random Network Communication Time Delay 103
4.4 Simulation of Networked Predictive Control Systems 106
4.4.1 Estimation of Network Transmission Delay 106
4.4.2 Off-line Simulation 106
4.4.3 Real-time Simulation 107
4.5 Implementation of Networked Predictive Control Systems 111

4.5.1 Software of Networked Control Systems ... 111
4.5.2 Networked Control System Test Rig ... 114
4.5.3 Practical Experiments ... 115
4.6 Conclusions ... 118
References ... 118

5 Robust H_∞ Control and Filtering of Networked Control Systems
Dong Yue, Qing-Long Han, James Lam ... 121
5.1 Introduction ... 121
5.2 Robust H_∞ Control of NCS ... 123
5.2.1 System Description and Preliminaries ... 123
5.2.2 H_∞ Performance Analysis ... 125
5.2.3 Robust H_∞ Controller Design ... 132
5.2.4 Numerical Examples ... 134
5.3 Robust H_∞ Filter Design of NCS ... 136
5.3.1 Modeling a Network-based Filter ... 136
5.3.2 H_∞ Performance Analysis of Filtering-error System ... 139
5.3.3 H_∞ Filter Design ... 142
5.3.4 Numerical Examples ... 144
5.4 Definition of Π_{ij} ... 147
5.5 Conclusions ... 149
References ... 150

6 Switched Feedback Control for Wireless Networked Systems
George Nikolakopoulos, Athanasia Panousopoulou, and Anthony Tzes ... 153
6.1 Introduction ... 153
6.2 Mathematical Modeling of NCS as a Switched System ... 155
6.3 Optimal Output Feedback Control ... 157
6.3.1 Gain Tuning of Output Feedback Parameter ... 158
6.3.2 Stability Investigation: Numerical Results ... 160
6.4 Experimental and Simulation Results ... 162
6.4.1 Switched Feedback Control Over GPRS ... 162
6.4.2 Switched Feedback Control Over IEEE 802.11b ... 169
6.4.3 Switched Optimal Feedback Control Over IEEE 802.11b in MANETs ... 185
6.5 Conclusions ... 193
References ... 193

7 Networked Control for T–S Fuzzy Systems with Time Delay
Dedong Yang and Huaguang Zhang ... 197
7.1 Introduction ... 197
7.2 Guaranteed Cost Networked Control for T–S Fuzzy Systems with Time Delay ... 199
7.3 Simulation Results ... 214

7.4 Robust H_∞ Networked Control for T–S Fuzzy Systems with Time Delay . . . 220
7.5 Simulation Results . . . 228
7.6 Conclusions . . . 231
References . . . 231

8 A Discrete-time Jump Fuzzy System Approach to NCS Design
Fuchun Sun and Fengge Wu . . . 233
8.1 Introduction . . . 233
8.1.1 Fundamental Issues in NCS . . . 234
8.1.2 Previous Work . . . 234
8.2 Modeling NCS . . . 235
8.2.1 Markov Characteristics of NCS . . . 236
8.2.2 Discrete-time Jump Fuzzy System . . . 237
8.3 State-feedback Controller Design . . . 238
8.3.1 The Closed-loop Model of an NCS . . . 238
8.3.2 Guaranteed Cost Controller Design . . . 239
8.3.3 Homotopy Algorithm . . . 245
8.4 Output Feedback Controller Synthesis of an NCS . . . 246
8.4.1 Fuzzy Observer Design . . . 246
8.4.2 Output Feedback Controller Design . . . 247
8.4.3 Simulation Example . . . 249
8.5 Neuro-fuzzy Controller Design . . . 253
8.5.1 Neuro-fuzzy Predictor . . . 255
8.5.2 Fuzzy Controller . . . 256
8.6 Conclusions . . . 256
References . . . 257

9 Networked Boundary Control of Damped Wave Equations
YangQuan Chen . . . 261
9.1 Introduction . . . 261
9.2 A Brief Introduction to the Smith Predictor . . . 262
9.3 Boundary Control of Damped Wave Equations with Large Delays . 263
9.4 Stability and Robustness Analysis . . . 265
9.5 Fractional Order Case – Problem Formulation . . . 268
9.6 Fractional Order Case – Robustness of Boundary Stabilization . . . 270
9.7 Fractional Order Case – Compensation of Large Delays in Boundary Measurement . . . 271
9.8 Conclusions . . . 272
References . . . 272

10 Coordination of Multi-agent Systems Using Adaptive Velocity Strategy
Wei Li and Xiaofan Wang 275
10.1 Introduction 275
10.2 The Constant Speed Vicsek Model 277
10.3 The Adaptive Velocity Model 278
10.4 Simulations and Discussions 281
10.5 Conclusions 288
References 290

11 Design of Robust Strictly Positive Real Transfer Functions
Wensheng Yu, Long Wang 293
11.1 Introduction 293
11.2 Definitions and Notation 294
11.3 Some Properties of SPR (WSPR) Regions 295
11.4 Characterization of SPR (WSPR) Regions 302
11.5 Robust SPR Synthesis: Intersection of WSPR Regions 307
11.6 Applications to Robust SPR Synthesis for Low-order Systems 310
11.6.1 The Third-order SPR Synthesis 312
11.6.2 The Fourth-order SPR Synthesis 316
11.7 Robust SPR Synthesis for Polynomial Segment of Arbitrary Order 324
11.7.1 Main Results 324
11.7.2 Design Procedure and Some Examples 330
11.7.3 Appendix: Proof of Lemma 11.17 332
11.8 Conclusions 337
References 338

Index 343